



# ARS60-HDA16384

ARS60 SSI/Parallel

**ABSOLUTE ENCODERS**

**SICK**  
Sensor Intelligence.



Illustration may differ



### Ordering information

Type	Part no.
ARS60-HDA16384	1031714

Other models and accessories → [www.sick.com/ARS60\\_SSI\\_Parallel](http://www.sick.com/ARS60_SSI_Parallel)

### Detailed technical data

#### Performance

<b>Number of steps per revolution (max. resolution)</b>	16,384 (14 bit)  Any number of steps from 00002 to 32768 possible. Always 5 characters in cleartext.
<b>Error limits G</b>	0.035° (binary number of steps) <sup>1)</sup> 0.046° (non-binary number of steps)
<b>Repeatability standard deviation <math>\sigma_r</math></b>	0.005° <sup>2)</sup>

<sup>1)</sup> In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

<sup>2)</sup> In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

#### Interfaces

<b>Communication interface</b>	Parallel data world
<b>Initialization time</b>	80 ms <sup>1)</sup>
<b>SSI</b>	
Code type	Binary
Code sequence parameter adjustable	CW (clockwise) increasing when viewing the clockwise rotating shaft Increasing, when turning the shaft For clockwise rotation, looking in direction "A" (see dimensional drawing)

<sup>1)</sup> Valid positional data can be read once this time has elapsed.

#### Electrical data

<b>Connection type</b>	Male connector, M23, 21-pin, radial
<b>Supply voltage</b>	10 ... 32 V DC
<b>Reverse polarity protection</b>	✓
<b>Short-circuit protection</b>	✓
<b>MTTFd: mean time to dangerous failure</b>	300 years (EN ISO 13849-1) <sup>1)</sup>

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

## Mechanical data

<b>Mechanical design</b>	Through hollow shaft
<b>Shaft diameter</b>	14 mm <sup>1)</sup>
<b>Weight</b>	0.3 kg
<b>Housing material</b>	Aluminum die cast
<b>Start up torque</b>	2.2 Ncm
<b>Operating torque</b>	1.6 Ncm
<b>Permissible shaft movement, axial static/dynamic</b>	± 0.5 mm, ± 0.2 mm
<b>Permissible shaft movement, radial static/dynamic</b>	± 0.3 mm, ± 0.1 mm
<b>Bearing lifetime</b>	3.6 x 10 <sup>9</sup> revolutions
<b>Angular acceleration</b>	≤ 500,000 rad/s <sup>2</sup>

<sup>1)</sup> Order collets for 6, 8, 10, and 12 mm and 1/4", 3/8", and 1/2" separately as accessories.

## Ambient data

<b>EMC</b>	According to EN 61000-6-2 and EN 61000-6-3 <sup>1)</sup>
<b>Enclosure rating</b>	IP64, with mating connector fitted (according to IEC 60529)
<b>Permissible relative humidity</b>	90 % (condensation of the optical scanning not permitted)
<b>Operating temperature range</b>	-20 °C ... +85 °C
<b>Storage temperature range</b>	-40 °C ... +100 °C
<b>Resistance to shocks</b>	50 g, 11 ms (according to EN 60068-2-27)
<b>Resistance to vibration</b>	20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

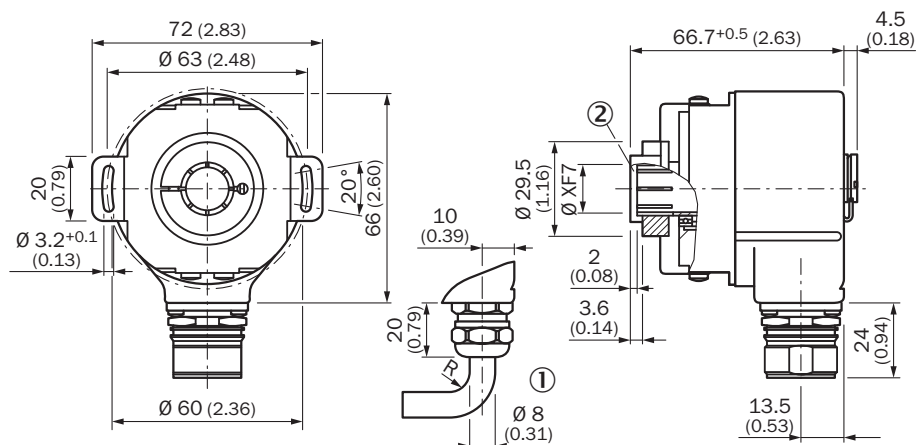
<sup>1)</sup> EMC according to the standards quoted is achieved if shielded cables are used.

## Classifications

<b>ECl@ss 5.0</b>	27270502
<b>ECl@ss 5.1.4</b>	27270502
<b>ECl@ss 6.0</b>	27270590
<b>ECl@ss 6.2</b>	27270590
<b>ECl@ss 7.0</b>	27270502
<b>ECl@ss 8.0</b>	27270502
<b>ECl@ss 8.1</b>	27270502
<b>ECl@ss 9.0</b>	27270502
<b>ETIM 5.0</b>	EC001486
<b>ETIM 6.0</b>	EC001486
<b>UNSPSC 16.0901</b>	41112113

### Dimensional drawing (Dimensions in mm (inch))

Through hollow shaft, radial plug connection M12 and M23



General tolerances according to DIN ISO 2768-mk

- ① R = min. bending radius 40 mm
- ② Insertion depth of mounting shaft min. 15 mm

### PIN assignment

• Allocation for encoder with 21-pin connector Single; Parallel Interface

PIN	Wire color by cable outlet	Binary	Gray	BCD	Description
1	Lilac	2 <sup>0</sup>	G <sub>0</sub>	2 <sup>0</sup> v.10 <sup>0</sup>	Data lines, outputs
2	White/brown	2 <sup>1</sup>	G <sub>1</sub>	2 <sup>1</sup> v.10 <sup>1</sup>	
3	White/green	2 <sup>2</sup>	G <sub>2</sub>	2 <sup>2</sup> v.10 <sup>2</sup>	
4	White/yellow	2 <sup>3</sup>	G <sub>3</sub>	2 <sup>3</sup> v.10 <sup>3</sup>	
5	White/gray	2 <sup>4</sup>	G <sub>4</sub>	2 <sup>4</sup> v.10 <sup>4</sup>	
6	White/pink	2 <sup>5</sup>	G <sub>5</sub>	2 <sup>5</sup> v.10 <sup>5</sup>	
7	White/blue	2 <sup>6</sup>	G <sub>6</sub>	2 <sup>6</sup> v.10 <sup>6</sup>	
8	White/red	2 <sup>7</sup>	G <sub>7</sub>	2 <sup>7</sup> v.10 <sup>7</sup>	
9	White/black	2 <sup>8</sup>	G <sub>8</sub>	2 <sup>8</sup> v.10 <sup>8</sup>	
10	Brown/green	2 <sup>9</sup>	G <sub>9</sub>	2 <sup>9</sup> v.10 <sup>9</sup>	
11	Brown/yellow	2 <sup>10</sup>	G <sub>10</sub>	2 <sup>10</sup> v.10 <sup>10</sup>	
12	Brown/gray	2 <sup>11</sup>	G <sub>11</sub>	2 <sup>11</sup> v.10 <sup>11</sup>	
13	Brown/pink	2 <sup>12</sup>	G <sub>12</sub>	2 <sup>12</sup> v.10 <sup>12</sup>	
14	Brown/blue	2 <sup>13</sup>	G <sub>13</sub>	2 <sup>13</sup> v.10 <sup>13</sup>	
15	Brown/red	2 <sup>14</sup>	G <sub>14</sub>	2 <sup>14</sup> v.10 <sup>14</sup>	
16	Green	Parity	Parity	Parity	
17	Pink	Store <sub>-</sub>	Store <sub>-</sub>	Store <sub>-</sub>	
18	Yellow	Enable <sub>-</sub>	Enable <sub>-</sub>	Enable <sub>-</sub>	
19	Brown	V/R <sub>-</sub>	V/R <sub>-</sub>	V/R <sub>-</sub>	
1)	Gray	SET	SET	SET	
20	Blue	GND	GND	GND	
21	Red	U <sub>s</sub>	U <sub>s</sub>	U <sub>s</sub>	
Housing		Screen	Screen	Screen	

1) Set line only possible with a cable outlet.

U<sub>s</sub> Supply voltage to the encoder (before commissioning, note must be taken of the type label of the encoder).

GND Zero volt connection to the encoder; electrically isolated from the housing. The voltage referred to GND is U<sub>s</sub>.

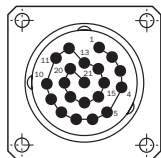
V/R<sub>-</sub> Forward/reverse: this input programs the counting direction of the encoder. If not connected, this input is -high-. If the encoder shaft, as viewed on the drive shaft, rotates in the clockwise direction, it counts in an increasing sequence. If it should count upwards when the shaft rotates in the anti-clockwise direction, this connection must be connected permanently to -low- level (zero volts).

Enable<sub>-</sub> This input activates the data output driver when a -low- level is applied. If not connected, this input is -low-. In the case of a -high- level, the outputs are in the tristate mode.

Store<sub>-</sub> This input stores the encoder data in Gray code when a -low- level is applied. This avoids a read error if the output data is requested in binary code. If this input is -low-, the data at the encoder output is stable, irrespective of whether the input shaft rotates. If not switched, this input is -high-.

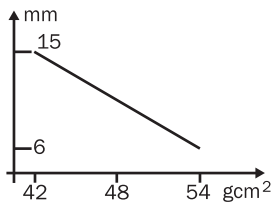
Parity This output supplies a -high- level when the binary checksum of the data bits is even.

SET This input serves to set the zero electronically. If the SET line is connected to U<sub>s</sub> for more than 100 ms, the mechanical position corresponds to the value 0.




View of the connector M23 fitted to the encoder body Single, Parallel

### Maximum revolution range



### Recommended accessories

Other models and accessories → [www.sick.com/ARS60\\_SSI\\_Parallel](http://www.sick.com/ARS60_SSI_Parallel)

	Brief description	Type	Part no.
Shaft adaptation			
	Collet for through hollow shaft, shaft diameter 6 mm, outer diameter 14 mm	SPZ-006-AD-D	2029192
	Collet for through hollow shaft, shaft diameter 8 mm, outer diameter 14 mm	SPZ-008-AD-D	2029194
	Collet for through hollow shaft, shaft diameter 10 mm, outer diameter 14 mm	SPZ-010-AD-D	2029196
	Collet for through hollow shaft, shaft diameter 12 mm, outer diameter 14 mm	SPZ-012-AD-D	2029197
	Collet for through hollow shaft, shaft diameter 1/2" (12.7 mm), outer diameter 14 mm	SPZ-1E2-AD-D	2029198
	Collet for through hollow shaft, shaft diameter 1/4" (6.35 mm), outer diameter 14 mm	SPZ-1E4-AD-D	2029193
	Collet for through hollow shaft, shaft diameter 3/8" (9.525 mm), outer diameter 14 mm	SPZ-3E8-AD-D	2029195

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